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K-means clustering is a simple unsupervised learning algorithm that is used to solve clustering problems. It follows a simple procedure of classifying a given data set into a number of clusters, defined by the letter "k," which is fixed beforehand. The clusters are then

positioned as points and all observations or data points are associated with the nearest cluster, computed, adjusted and then the process starts over using the new adjustments until a desired result is reached.

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The modified version of GA has used a new adaptive position crossover technique to improve the convergence of the GA. The chapter emphasizes the significance of metaheuristic approaches in data clustering. Because of a global optimization technique, the GA has been used in k?means clustering. The performance of clustering is dependent on the initial cluster centers and the outliers present in the dataset. k?means clustering is also stuck in a local minimum.

Adaptive Position-Based Crossover in the Genetic Algorithm ...

K-means clustering is a type of unsupervised learning, which is used when you have unlabeled data (i.e., data without defined categories or groups). The goal of this algorithm is to find groups in the data, with the number of groups represented by the variable K. The algorithm works iteratively to assign each data point to one of K groups based on the features that are provided. Data points are clustered based on feature similarity.

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k-means clustering - Wikipedia

K-Means clustering algorithm is defined as a unsupervised learning methods having an iterative process in which the dataset are grouped into k number of predefined non-overlapping clusters or subgroups making the inner points of the cluster as similar as possible while trying to keep the clusters at distinct space it allocates the data points to a cluster so that the sum of the squared distance between the clusters centroid and the data point is at a minimum, at this position the centroid of ...

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In this study, a k-means clustering based feature selection is proposed. It is assumed that redundant features are located in the same cluster, whereas irrelevant features do not belong to any clusters.

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The presented k-means-based algorithm incorporates a weighting function employing a measure of outlyingness in order to automatically assign a weight to each observation. While a high weight indicates that an observation is part of a cluster, a low weight refers to a potential outlier.

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