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The ATmega8 has 3 counters, 2 8bit counters and 1 16bit counter. Since all 3 counters have unique registers and special functions I will break this chapter subsections by counter insted of my usual hardware, theory and software format.

COUNTERS ON THE ATmega8 - QEEWiki

ATmega8 comes with two 8-bit and one 16-bit

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timer. This means that there are 3 sets of timers, each with the ability to count at different rates. The two 8-bit counters can count to 255 whilst the 16-bit counter can count to 65,536.

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This project can measure capacitance and inductance using the Atmega8 microcontroller and the code is written in Bascom AVR. The limitations of this project is Inductance Range: 0.1?H to 2H... SD/SDHC Card Interfacing with ATmega8 /32 (FAT32 implementation)

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Say we want to counter to count to 1ms, in

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the first example we just lived with the fact that our 1ms timer was actually a 1.024ms timer. In order to get a true 1ms we need to count to 0xF9, which is only 6 lower than the max. So what we need to do is add 6 to the register when it overflows to 0.

Timers on the ATmega8 - QEEWiki

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hardware as shown, and feed the code to atmega8. when the work is finished, slowly turn the 10k potmeter and check the result. as coded, if ...

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as a frequency counter with I2C output. So
what we are going to make is a frequency
counter circuit which can also be called as a
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This is a simple javascript calculator I wrote to help me make timing calculations while working with the timers on AVR microcontrollers. The same calculations applies for all microcontrollers but the prescaler options only contain the ones possible on an AVR microcontroller (the configuration numbe

AVR Timer Calculator | Eleccelerator

In this picture from Atmega8 documentation Fast PWM mode is explained. Counter(8bit)

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counts from 0x00 to 0xFF and restarts from 0x00. In not inverting mode OC2 is cleared when counter match value in OCR2 register and set at 0x00. In inverting mode OC2 is set when counter match value in OCR2 register and cleared at 0x00.

Atmega8 PWM control(frequency,polarity,duty cycle ...

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