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Sample questions asked in the 4th edition of System Dynamics: Consider the system shown in Figure 1. It is desired to design a Pill controller $G_c(s)$ such that the dominant closed-loop poles are located at $s = -1 \pm j$. For the PID controller, choose $a = 0.5$, and then determine the values of K and b . Draw a root locus plot with MATLAB. Figure 1 PID-controlled system.

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