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Based on the preceding discussion, the following parameter estimation problem can be formulated and considered in the subsequent sections. THE GENERAL PARAMETER ESTIMATION PROBLEM: Given measurements lk lk = !!k (~) + lA; k = 1,2, ... ,N (13) where E [lA I = 0 E (lA,!j1 = R 8 k j, estimate the parameters ~.

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first used by Czekanowski in 1913 and discovered anew by Sorensen (1948): 2. S. 2. a S a bc = ++ (12.3) where . S. S = Sorensen's similarity coefficient . This index can also be modified to a coefficient of . dissimilarity. by taking its inverse: Sorensen's dissimilarity coefficient 1= ? S s (12.4)

PART FOUR ESTIMATING COMMUNITY PARAMETERS

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The last form suggests again a recursive estimation procedure for the determination of the conditional density. It is thus possible to compute filtered and prediction distributions in a forward (filtering) recursion, and then execute a backward recursion with each smoothed distribution p (? t ? Z T) relying upon the quantities calculated in the forward run and the previous (in reverse time ...